

Finite Elements (1D)

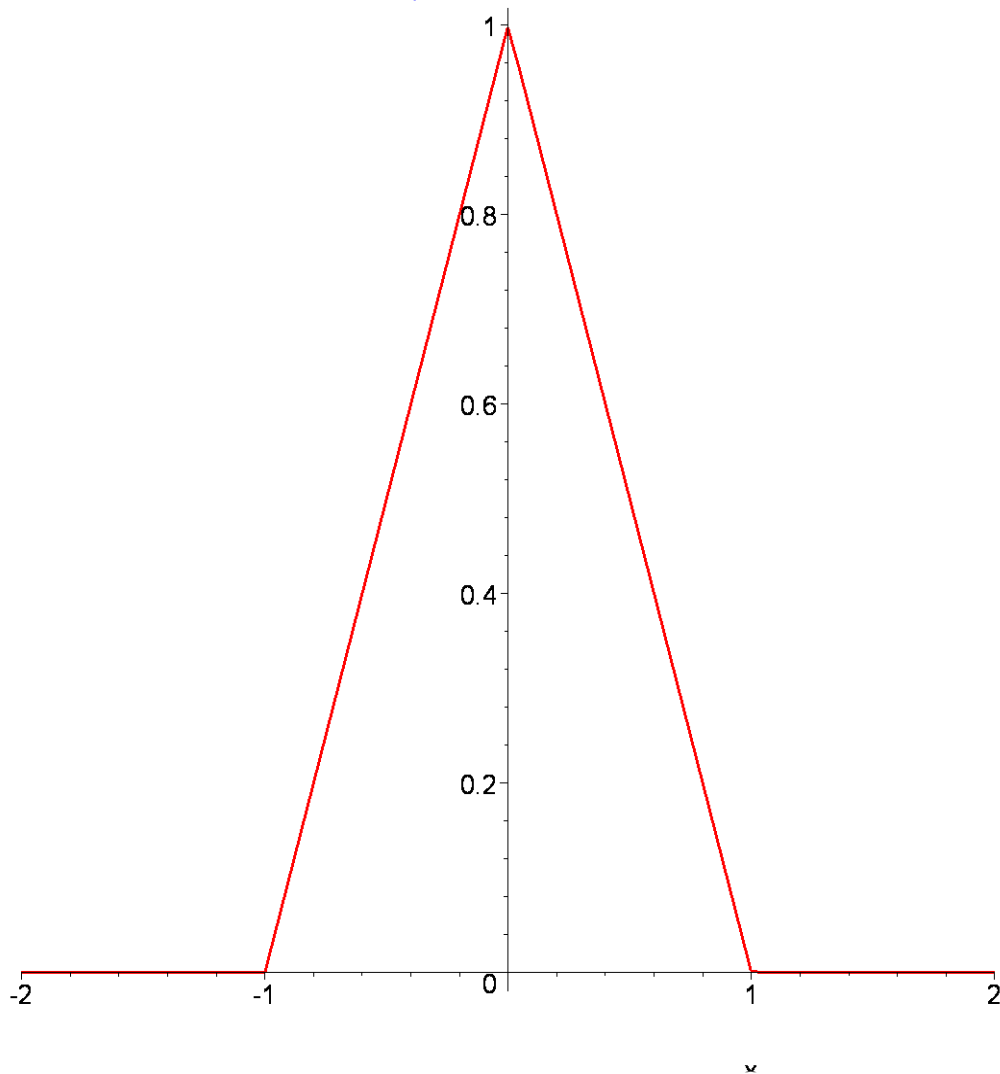
```
> restart;  
> with(LinearAlgebra):
```

- Building a basis Φ of test and ansatz functions

- Template for basis functions f_0

```
> f0 := piecewise(x<-1, 0, x<0, x+1, x<=1, 1-x, 0);  
> plot(f0, x=-2..2, thickness=3);
```

$$f_0 := \begin{cases} 0 & x < -1 \\ x + 1 & x < 0 \\ 1 - x & x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$



```
>
```

- Now, specify mesh width h and position x_0

```
> n := 3;  
> h := [seq(1/(n+1), i=1..n)];  
> x0 := [seq(i/(n+1), i=1..n)];
```

```
n := 3
h := [1/4, 1/4, 1/4]
x0 := [1/4, 1/2, 3/4]
```

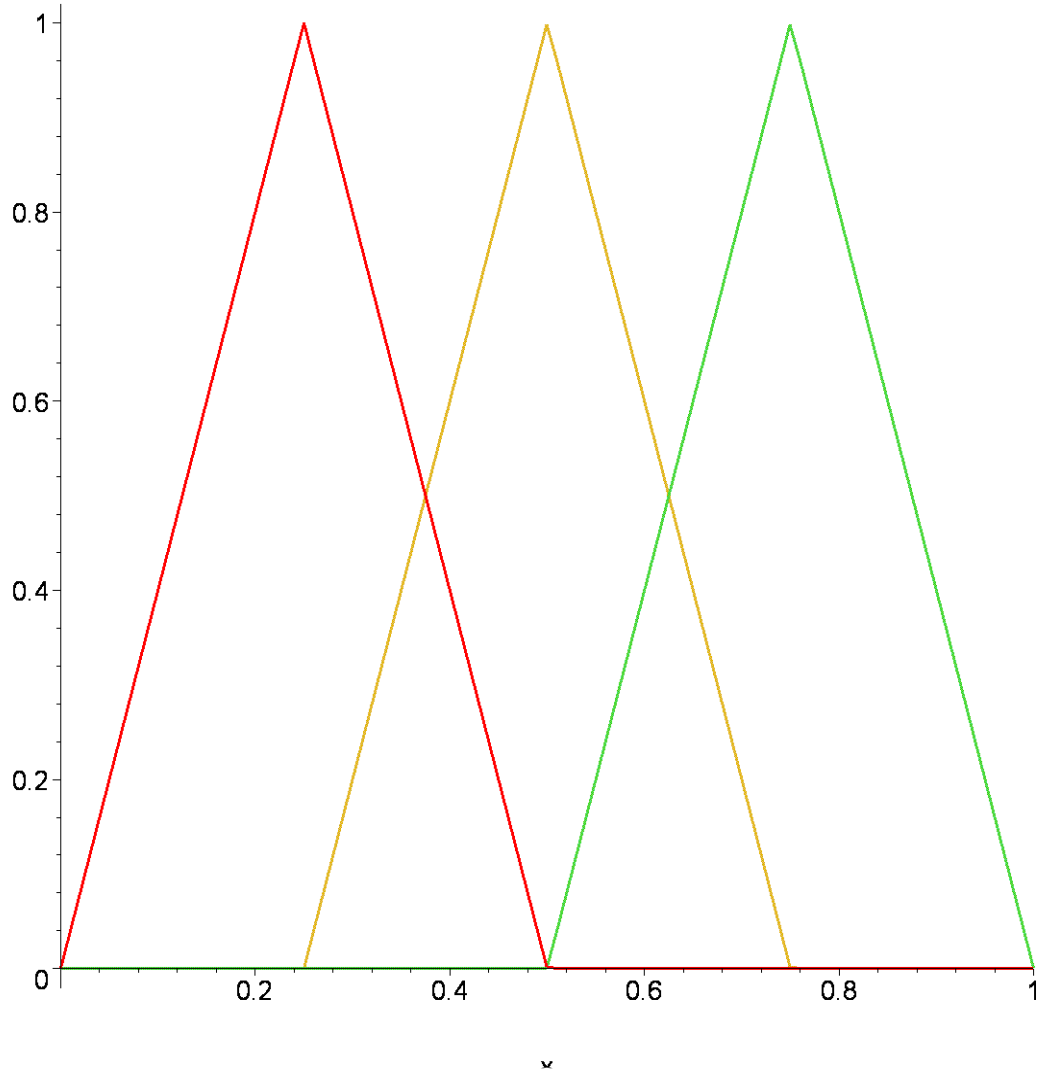
```
>
```

- Define the basis functions

```
> for i from 1 to n do
    phi[i] := convert(subs(x=(x-x0[i])/h[i],f0), piecewise,
x):
od:
```

- Plot the basis functions

```
> plot({seq(phi[i], i=1..n)}, x=0..1,thickness=3);
```



```
>
```

- Stiffness matrix and mass matrix

- Stiffness matrix A

$$\text{Stiffness matrix: } a_{i,j} := \int_0^1 \left(\frac{\partial}{\partial x} \phi_i \right) \left(\frac{\partial}{\partial x} \phi_j \right) dx$$

```
> A := Matrix(n,n):  
  for i from 1 to n do  
    for j from 1 to n do  
      A[i,j] := int( diff(phi[i],x)*diff(phi[j] ,x),  
x=0..1);  
    od;  
  od;  
  A;
```

$$\begin{bmatrix} 8 & -4 & 0 \\ -4 & 8 & -4 \\ 0 & -4 & 8 \end{bmatrix}$$

[>

- Mass matrix B

$$\text{Mass matrix: } b_{i,j} := \int_0^1 \phi_i \phi_j dx$$

```
> B := Matrix(n,n):  
  for i from 1 to n do  
    for j from 1 to n do  
      B[i,j] := int(phi[i]*phi[j], x=0..1);  
    od;  
  od;  
  B;
```

>

$$\begin{bmatrix} \frac{1}{6} & \frac{1}{24} & 0 \\ \frac{1}{24} & \frac{1}{6} & \frac{1}{24} \\ 0 & \frac{1}{24} & \frac{1}{6} \end{bmatrix}$$

[>

- A very simple example

We solve the (embarrassingly simple) equation $u = x(1-x)$ using the bilinear form

$$b(u, v) = \int_0^1 u(x) v(x) dx.$$

The result u_h in V_h minimises the L2 norm of $u_h - x(1-x)$.

```
> bb := x*(1-x);
> b := Vector(n):
  for i from 1 to n do
    b[i] := int(phi[i]*bb, x=0..1):
  od:
b;
```

$$bb := x(1-x)$$

$$\begin{bmatrix} \frac{17}{384} \\ \frac{23}{384} \\ \frac{17}{384} \end{bmatrix}$$

- Solution

```
> u := LinearSolve(B,b); evalf(%);
```

\underline{B} is the system matrix, \underline{b} the right hand side.

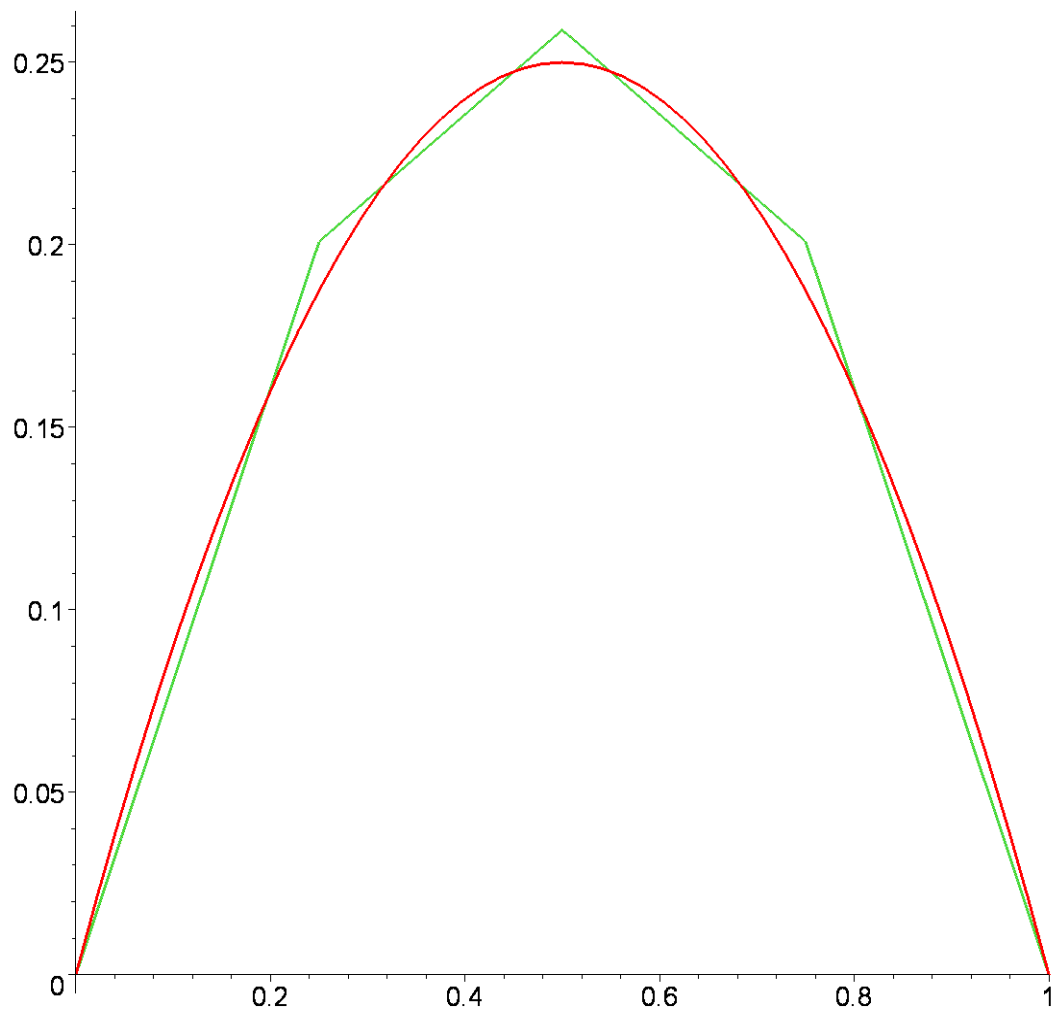
The respective piecewise linear function uu is obtained as a linear combination of the basis functions \underline{bs}

```
> uu := convert(add(u[i]*phi[i],i=1..n), piecewise, x):
```

$$u := \begin{bmatrix} \frac{45}{224} \\ \frac{29}{112} \\ \frac{45}{224} \end{bmatrix}$$

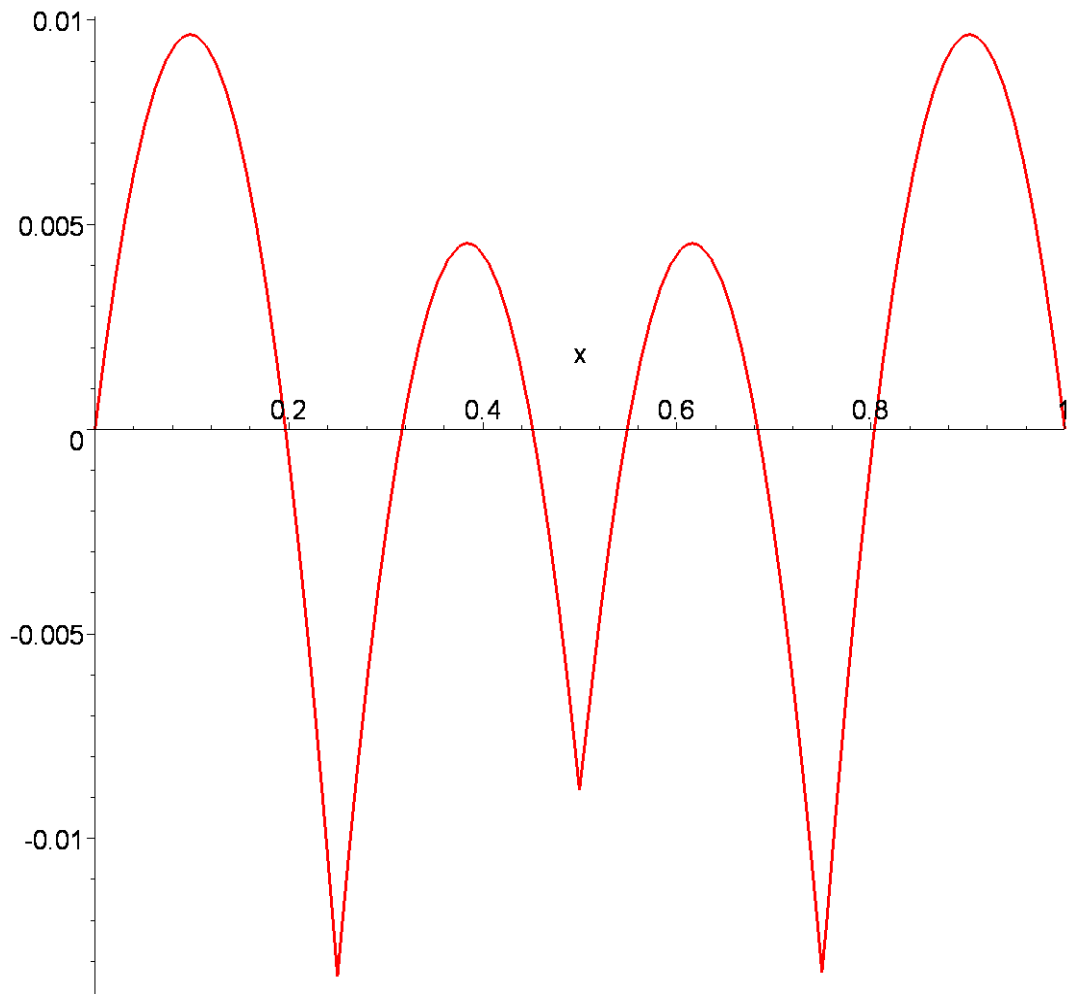
$$\begin{bmatrix} 0.2008928571 \\ 0.2589285714 \\ 0.2008928571 \end{bmatrix}$$

```
> plot({uu,bb}, x=0..1,thickness=3);
```



```
> plot(bb-uu, x=0..1,thickness=3);
```

The difference between bb and the approximation uu



[>

- Poisson's equation in 1D

For Poisson's equation, A (the stiffness matrix) is the system matrix.

We can retain $x(1-x)$ as the right hand side (thus solving the equation $-u'' = x(1-x)$), so b is still our right hand side of the Linear System.

The equation can still be solved exactly:

```
> usol := x -> -x^3/6 + x^4/12 + x/12;
diff( -usol(x), x,x); usol(0); usol(1);
```

$$\text{usol} := x \rightarrow -\frac{1}{6}x^3 + \frac{1}{12}x^4 + \frac{1}{12}x$$

$$x - x^2$$

$$0$$

$$0$$

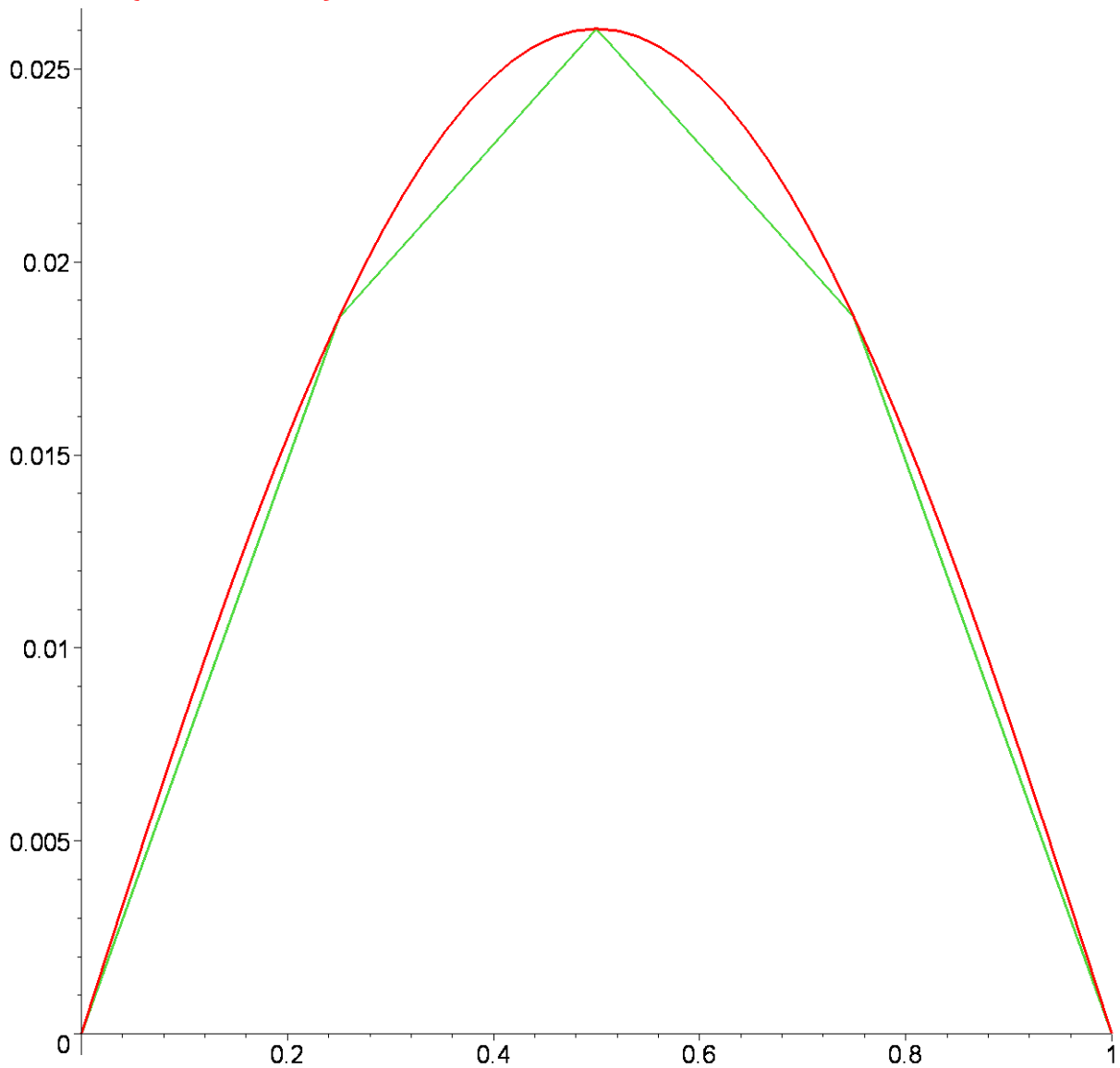
The FE solution, however, is:

```
> u := LinearSolve(A,b); evalf(%);
```

$$u := \begin{bmatrix} \frac{19}{1024} \\ \frac{5}{192} \\ \frac{19}{1024} \end{bmatrix}$$

$$\begin{bmatrix} 0.01855468750 \\ 0.02604166667 \\ 0.01855468750 \end{bmatrix}$$

```
> uu := convert(add(u[i]*phi[i],i=1..n), piecewise, x):
> plot({uu,usol(x)}, x=0..1,thickness=3);
```



```
>
```

- Using a Hierarchical Basis

Define number of levels and number of basis functions.

```
> Lmax := 1;
```

```
n := 2^(Lmax+1)-1;
```

```
Lmax := 1
```

```
n := 3
```

Define the basis functions:

```
> for level from 0 to Lmax do  
  h := 2^(-level);  
  for i from 0 to 2^level-1 do  
    x0 := (1/2 + i)*h;  
    print(2^level+i);  
    phi[2^level+i] := convert(subs(x=(x-x0)/(h/2),f0),  
  piecewise, x);  
  end do:  
end do:
```

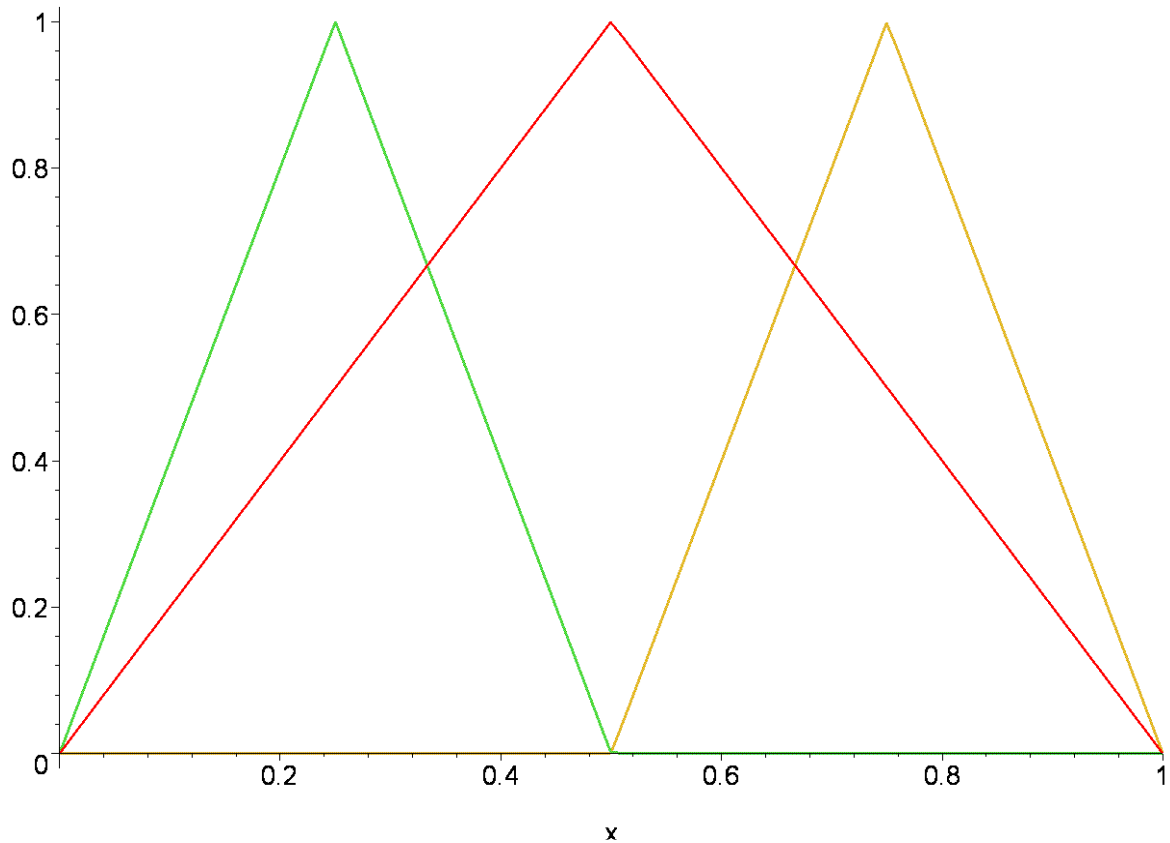
```
1
```

```
2
```

```
3
```

and plot them:

```
> plot({seq(phi[i], i=1..n)}, x=0..1,thickness=3);
```



Compute stiffness matrix

Stiffness matrix: $a_{i,j} := \int_0^1 \left(\frac{\partial}{\partial x} \phi_i \right) \left(\frac{\partial}{\partial x} \phi_j \right) dx$

```
> A := Matrix(n,n):  
  for i from 1 to n do
```



```

    for j from 1 to n do
      A[i,j] := int( diff(phi[i],x)*diff(phi[j] ,x),
x=0..1);
    od;
  od;
  A;

```

$$\begin{bmatrix} 4 & 0 & 0 \\ 0 & 8 & 0 \\ 0 & 0 & 8 \end{bmatrix}$$

Compute right hand side (same rhs function, but other test functions)

```

> bb := x*(1-x);
  b := Vector(n):
  for i from 1 to n do
    b[i] := int(phi[i]*bb, x=0..1):
  od:
  b;

```

$$\begin{array}{l} \text{bb} := x(1-x) \\ \begin{bmatrix} \frac{5}{48} \\ \frac{17}{384} \\ \frac{17}{384} \end{bmatrix} \end{array}$$

Solve system of linear equations (very easy, because A is diagonal):

```

> u := LinearSolve(A,b);

```

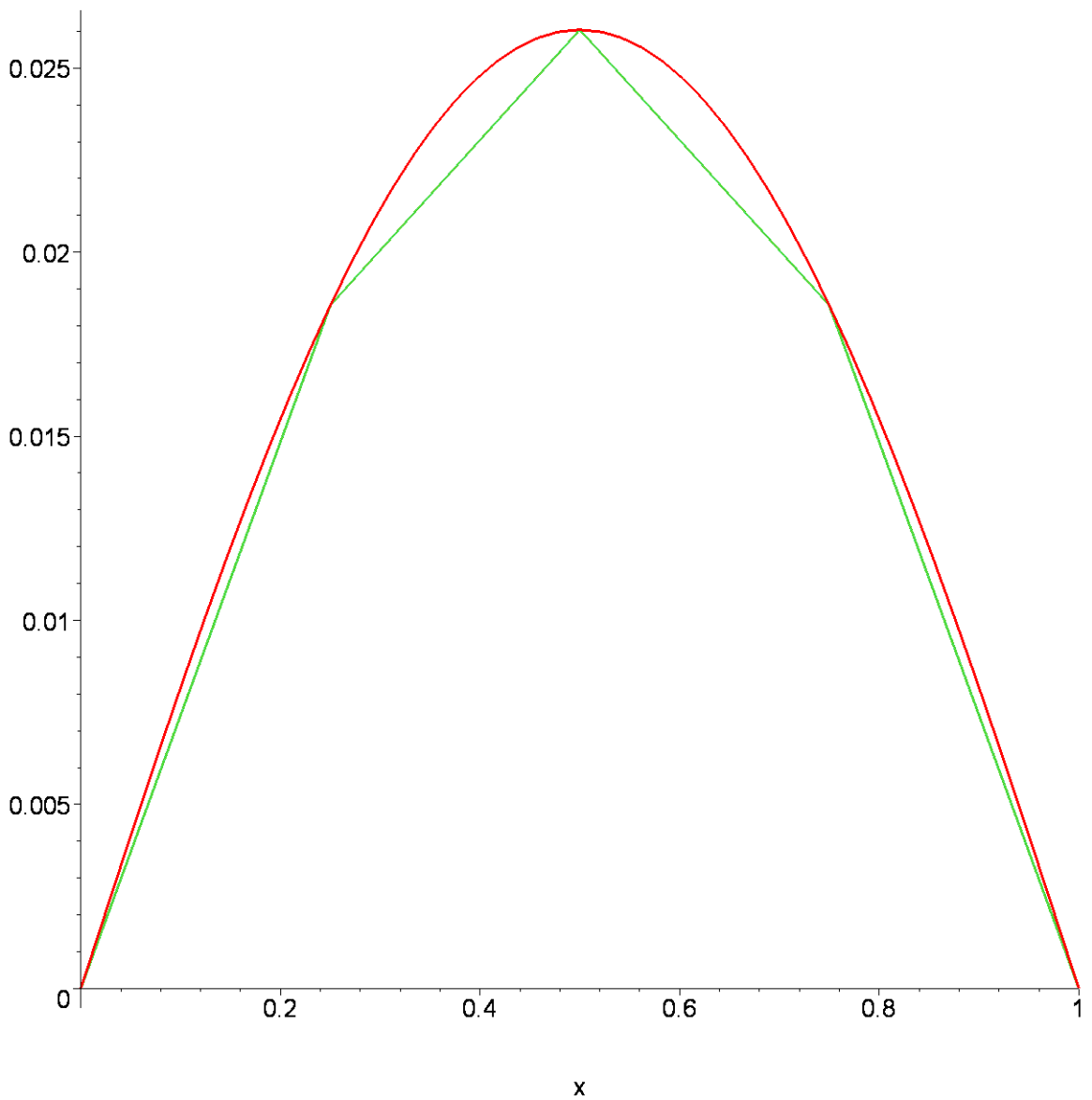
$$u := \begin{bmatrix} \frac{5}{192} \\ \frac{17}{3072} \\ \frac{17}{3072} \end{bmatrix}$$

And plot the solution:

```

> uu := convert(add(u[i]*phi[i],i=1..n), piecewise, x):
  plot({uu,usol(x)}, x=0..1,thickness=3);

```



[Note: The solution is identical to the previous one:
[the basis functions are different, but the function space is the same!
[>
[>