

Algorithms of Scientific Computing

Discrete Sine Transform (DST)

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DFT and Symmetry

	INPUT		TRANSFORM
real symmetry	$f_n \in \mathbb{R}$	→	Real DFT (RDFT)
even symmetry	$f_n = f_{-n}$	→	Discrete Cosine Transform (DCT)
odd symmetry	$f_n = -f_{-n}$	→	Discrete Sine Transform (DST)

“QUARTER-WAVE”	INPUT		TRANSFORM
even symmetry	$f_n = f_{-n-1}$	→	QW-DCT
odd symmetry	$f_n = -f_{-n-1}$	→	QW-DST

Real-valued Input Data with “Odd” Symmetry

Given: $2N$ input data f_{-N+1}, \dots, f_N , all $f_n \in \mathbb{R}$, with

$$f_{-n} = -f_n, \quad \text{in particular} \quad f_0 = f_N = f_{-N} = 0$$

The DFT then has the following form:

$$\begin{aligned} F_k &= \frac{1}{2N} \sum_{n=-N+1}^N f_n \omega_{2N}^{-nk} \\ &= \frac{1}{2N} \left(\underbrace{f_0}_{=0} + \sum_{n=1}^{N-1} \left(f_n \omega_{2N}^{-nk} + f_{-n} \omega_{2N}^{nk} \right) + \underbrace{f_N}_{=0} \omega_{2N}^{-Nk} \right) \\ &= \frac{1}{2N} \sum_{n=1}^{N-1} f_n \left(\omega_{2N}^{-nk} - \omega_{2N}^{nk} \right) = \frac{-j}{N} \sum_{n=1}^{N-1} f_n \sin \left(\frac{\pi nk}{N} \right). \end{aligned}$$

Symmetry in the Coefficients

Transform to f_n with symmetry $f_{-n} = -f_n$ gives:

$$F_k = \frac{-j}{N} \sum_{n=1}^{N-1} f_n \sin\left(\frac{\pi nk}{N}\right) \quad \text{for } k = -N+1, \dots, N.$$

Same symmetrie in the coefficients F_k :

$$F_{-k} = \frac{-j}{N} \sum_{n=1}^{N-1} f_n \sin\left(\frac{\pi n(-k)}{N}\right) = \frac{-j}{N} \sum_{n=1}^{N-1} f_n \left(-\sin\frac{\pi nk}{N}\right) = -F_k$$

⇒ leads to the same (up to scaling) sine transform

Discrete Sine Transform (DST)

From DFT of real-valued, odd symmetric data:

$$F_k = -\frac{i}{N} \sum_{n=1}^{N-1} f_n \sin\left(\frac{\pi nk}{N}\right), \quad k = 1, \dots, N-1.$$

Analogue calculation for IDFT gives:

$$f_n = 2i \sum_{k=1}^{N-1} F_k \sin\left(\frac{\pi nk}{N}\right), \quad n = 1, \dots, N-1.$$

⇒ definition of the discrete sine transform ($\hat{F}_k := iF_k$):

$$\hat{F}_k = \frac{1}{N} \sum_{n=1}^{N-1} f_n \sin\left(\frac{\pi nk}{N}\right), \quad f_n = 2 \sum_{k=1}^{N-1} \hat{F}_k \sin\left(\frac{\pi nk}{N}\right),$$

Computation of the Discrete Sine Transform

Via pre-/postprocessing:

- (1) generate $2N$ vector with odd symmetry

$$x_{-k} = -x_k \quad \text{for } k = 1, \dots, N-1$$

$$x_0 = x_N = 0$$

- (2) coefficients X_k via fast, real-valued FFT on vector x
- (3) postprocessing: $\widehat{X}_k = -\text{Im}\{X_k\}$ for $k = 1, \dots, N-1$.
- (4) if necessary: scaling

Summary: Survey on DCT/DST Variants

Symmetry properties \Leftrightarrow how is data continued at boundaries:

beg. \ end	even	odd
even	x	x
odd	x	x

\Rightarrow 4 possibilities

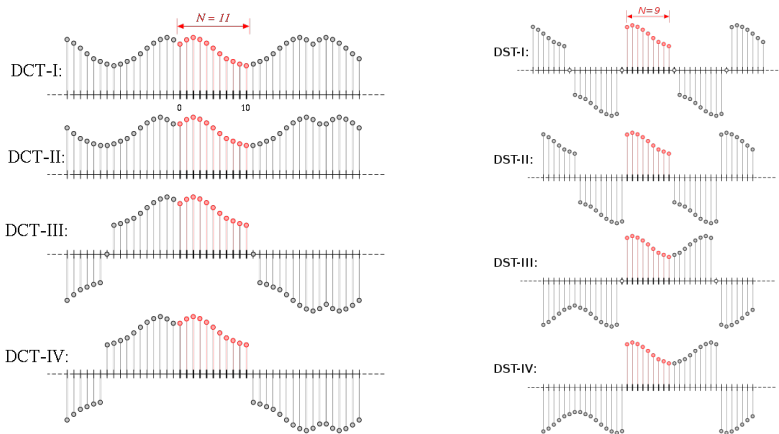
beg. \ end	mirror	copy
mirror	x	x
copy	x	x

\Rightarrow 4 possibilities

\Rightarrow **total:** 16 possibilities (8 DCT, 8 DST)

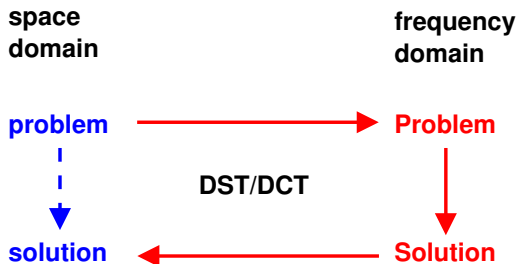
Summary: Survey on DCT/DST Variants (2)

Common schemes of DCT (left) and DST (right) (source: wikipedia):



Application: DCT/DST for PDE (Spectral Methods)

nice application in exercise sessions: DST for Fast Poisson Solver



Attention: also limits/problems for using DFT with PDE:

- irregular (i.e. non-rectangular) domains
 - variable coefficients in problem
- ⇒ other methods: FVM, FEM (fast linear solvers, multigrid, etc.)