

Algorithms for Scientific Computing

Hierarchical Methods

– Interpolation, Approximation and Classification –

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Part I

Approximation, Classification – Towards Data Mining

Recall Interpolation Problem

Interpolation problem:

- N ansatz functions: $g_k(x)$, $k = 0, \dots, N - 1$
- N supporting points: x_n , $n = 0, \dots, N - 1$
- N interpolation values: f_n , $n = 0, \dots, N - 1$
- find N coefficients c_k such that at all supporting points

$$f_n = \sum_{k=0}^{N-1} c_k g_k(x_n)$$

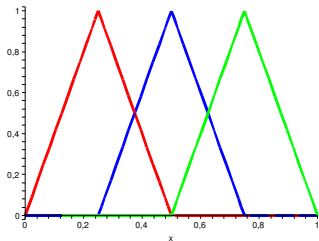
How to choose the $g_k(x)$?

- polynomials $\phi_j(x) = x^j \rightsquigarrow$ numerics lecture ...
- sine and cosine functions, or $\phi_k(x) = e^{ikx}$
 \rightsquigarrow Discrete Fourier Transform: $f_n = \sum_{k=0}^{N-1} F_k e^{i2\pi nk/N}$
- now: piecewise linear functions

Piecewise Linear Interpolation

$$\varphi_k(x) := \begin{cases} \frac{1}{h_{k-1}}(x - x_{k-1}) & x_{k-1} < x < x_k \\ \frac{1}{h_k}(x_{k+1} - x) & x_k < x < x_{k+1} \\ 0 & \text{otherwise} \end{cases}$$

with $h_k := x_{k+1} - x_k$



Solution of the interpolation problem?

- ansatz function $\varphi_k(x) = 1$ at $x = x_k$
- ansatz function $\varphi_k(x) = 0$ at all $x_n \neq x_k$
- thus: $c_k = f_k$ for all k

Too trivial? \rightsquigarrow consider a slightly more complicated problem ...

Classification in Data Mining

Now for something completely different?

- We consider another application: classification in data mining (our contribution to “Big Data”)
- Aim is to extract new and (hopefully) useful information (out of data bases, etc.)



- We consider *predictive modelling* in data mining:
 - Forecast values on new, previously unseen data
 - Prediction based on given set of data points (*training data*)

Problem Setting: Binary Classification

Classification aims to

- assign a “correct” class label $k \in K$
- to all data points \vec{x} in some d -dimensional feature space $\Omega = \mathbb{R}^d$
- based on set S of pre-classified data points for training

$$S := \{(\vec{x}_i, y_i) \in \Omega \times K\}_{i=1}^m$$

- Here: binary classification, for us $K := \{+1, -1\}$

Tasks (examples):

- Did a passenger of the Titanic survive?
(dimensions: age, male/female, income, ...)?
- Is a bank customer credit-worthy?
(dimensions: income, type of house, ...)?
- Will personalized advertising pay off for a certain person?
(dimensions: interests, previous purchases, ...)

Classification

Many approaches exist:

- Decision trees
- Rule-based classifiers (decision rules)
- Instance-based classifiers (k -Nearest Neighbour, ...)
- Probabilistic (Bayes) classifiers
- Based on function representation (artificial neural networks, support vector machines, ...)

Claim of Discretization-Based Classification:

- All depend at least quadratically on size of training set (think of classification based on comparisons of data points)
- Approach based on discretization of Ω (i.e., approximate S by a function) would allow linear training time
- roadblock: curse of dimensionality
⇒ possible solution: sparse grids! (to be discussed ...)

Classification using d -Dimensional Functions

- Given: training set (normalized)

$$\mathcal{S} := \left\{ (\vec{x}_i, y_i) \in [0, 1]^d \times \{+1, -1\} \right\}_{i=1}^m$$

- Assume: training data obtained by random sampling of unknown function f (possibly disturbed by noise)
- Find approximation f_N of f :

$$f(\vec{x}) \approx f_N(\vec{x}) = \sum_{j=1}^N v_j \phi_j(\vec{x})$$

\rightsquigarrow following our “coefficients and basis functions” approach

- To determine classification of a new data point \vec{x} :
 - Compute $f_N(\vec{x})$
 - Classify as $+1$, if $f_N(\vec{x}) \geq 0$; otherwise -1

First: Classification in 1D

- Given: training set (normalized)

$$S := \{(\vec{x}_i, y_i) \in [0, 1] \times \{+1, -1\}\}_{i=1}^m$$

- Find approximation f_N of f :

$$f(x) \approx f_N(x) = \sum_{j=1}^N v_j \phi_j(x)$$

- Classical approach: minimize quadratic error

$$\sum_{i=1}^m (f_N(x_i) - y_i)^2 \stackrel{!}{=} \min \quad \Leftrightarrow \quad \sum_{i=1}^m \left(\sum_{j=1}^N v_j \phi_j(x_i) - y_i \right)^2 \stackrel{!}{=} \min$$

- Remember solution via “least squares”: $G^T G v = G^T y$
where $G_{ij} = \phi_j(x_i)$

Classification in 1D – Least Squares Solution

- minimize quadratic error \rightsquigarrow find values v_j that minimize

$$\sum_{i=1}^m \left(\sum_{j=1}^N v_j \phi_j(x_i) - y_i \right)^2 \quad \text{or} \quad \sum_{i=1}^m \left(\sum_{j=1}^N G_{ij} v_j - y_i \right)^2$$

- approach: set all partial derivatives $\frac{\partial}{\partial v_k}$ to zero

$$\begin{aligned} \frac{\partial}{\partial v_k} \left(\sum_{i=1}^m \left(\sum_{j=1}^N G_{ij} v_j - y_i \right)^2 \right) &= \sum_{i=1}^m \frac{\partial}{\partial v_k} \left(\sum_{j=1}^N G_{ij} v_j - y_i \right)^2 = 0 \\ \Leftrightarrow \sum_{i=1}^m 2 \left(\sum_{j=1}^N G_{ij} v_j - y_i \right) G_{ik} &= 2 \sum_{i=1}^m \left(\sum_{j=1}^N G_{ik} G_{ij} v_j - G_{ik} y_i \right) = 0 \\ \Leftrightarrow \sum_{i=1}^m \sum_{j=1}^N G_{ik} G_{ij} v_j - \sum_{i=1}^m G_{ik} y_i &= \sum_{i=1}^m G_{ik} \underbrace{\sum_{j=1}^N G_{ij} v_j}_{=(Gv)_i} - \underbrace{\sum_{i=1}^m G_{ik} y_i}_{=(G^T y)_k} = 0 \\ &\underbrace{\hspace{10em}}_{=(G^T Gv)_k} \end{aligned}$$

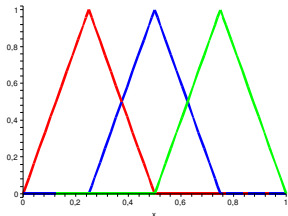
Classification in 1D – Ansatz Functions?

How to choose the $\phi_j(x)$?

- polynomials $\phi_j(x) = x^j \rightsquigarrow$ numerics lecture ...
- sine and cosine functions, or $\phi_j(x) = e^{ijx}$
 \rightsquigarrow Discrete Fourier Transform! (see tutorials)
- new idea: piecewise linear functions

$$\varphi_j(x) := \begin{cases} \frac{1}{h}(x - \xi_{j-1}) & \xi_{j-1} < x < \xi_j \\ \frac{1}{h}(\xi_{j+1} - x) & \xi_j < x < \xi_{j+1} \\ 0 & \text{otherwise} \end{cases}$$

with grid points $\xi_j := j \cdot h$



How difficult is it to compute the solution?

Classification with Piecewise Linear Functions

Structure of the matrix G , where $G_{ij} = \varphi_j(x_i)$:

- assume N_j data points per interval $[\xi_{j-1}, \xi_j]$
- these N_j data points generate N_j non-zeros in column $G_{*,j-1}$ and N_j non-zeros in column $G_{*,j}$
- Example structure (3 basis functions, 4 intervals, 10 data points):

$$G^T := \left(\begin{array}{cc|ccc|cccc|c} * & * & * & * & * & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & * & * & * & * & * & * & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * & * & * & * & * \end{array} \right)$$

- $G^T G$ is thus a tridiagonal matrix
- system $G^T G v = G^T y$ therefore easy to solve

What problems do you expect?

Classification with Piecewise Linear Functions

Possible Problems:

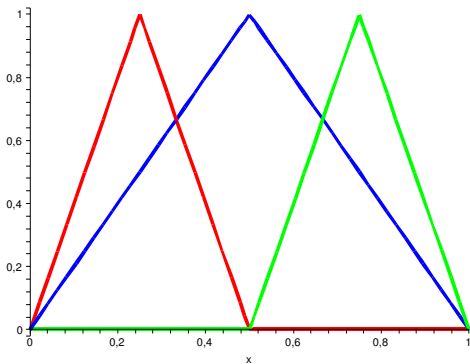
- How to choose resolution h ?
 - too fine: intervals might be empty (and undetermined)
 - too coarse: bad approximation of signal
 - too fine: over-approximation of noisy signal
- What if data points are not equally distributed?
 - fine resolution required at clustered data points
 - coarse resolution required in “empty” regions

Requirements and Possible Approaches:

- Adaptive placement of grid points
 - invest grid points where the data points are clustered
- “Regularization” for noisy data
 - avoid over-approximation via additional requirements
 - require “smooth” approximation and/or limit gradients, e.g.

Hierarchical Basis

- piecewise linear functions with multi-level resolution:



- coarse-level functions (with wide support) \rightarrow never “too fine”
- also “never too coarse”? \rightarrow interaction of fine and coarse?

Define Hierarchical Basis

- consider mesh size $h_n = 2^{-n}$ and grid points $x_{n,i} = i \cdot h_n$
- Define “mother of all hat functions”

$$\phi(x) := \max\{1 - |x|, 0\}$$

- nodal basis then $\Phi_n := \{\phi_{n,i}, 0 \leq i \leq 2^n\}$ with

$$\phi_{n,i}(x) := \phi\left(\frac{x - x_{n,i}}{h_n}\right)$$

- hierarchical basis combines $\widehat{\Phi}_n := \{\phi_{n,i}, i = 1, 3, \dots, 2^n - 1\}$ (only odd indices) and defines basis as

$$\Psi_n := \bigcup_{l=1}^n \widehat{\Phi}_l$$

- hierarchical basis still represents all piecewise linear functions:
 $\text{span}(\Phi_n) = \text{span}(\Psi_n)$

Classification with Hierarchical Basis Functions

Structure of the matrix G , where $G_{ij} = \varphi_j(x_i)$,
 where $\{\varphi_1, \varphi_2, \varphi_3\} = \{\phi_{2,1}, \phi_{1,1}, \phi_{2,3}\}$:

- again assume N_j data points per interval $[\xi_{j-1}, \xi_j]$
- Example structure then (again with 3 basis functions, 4 intervals, 10 data points):

$$G^T := \left(\begin{array}{cc|ccc|cccc|c} * & * & * & * & * & 0 & 0 & 0 & 0 & 0 \\ * & * & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & * & * & * & * & * \end{array} \right)$$

- $G^T G$ no longer tridiagonal \rightarrow expect a denser matrix
- how difficult is it to solve $G^T G v = G^T y$?
 \rightarrow later in the lecture
- efficiency of this approach for data mining?
 \rightarrow requires hierarchical basis in high dimensions

The Curse of Dimensionality

- Recall: d -dimensional training set

$$\mathcal{S} := \left\{ (\vec{x}_i, y_i) \in [0, 1]^d \times \{+1, -1\} \right\}_{i=1}^m$$

- How many grid points necessary for classification?
- Nodal basis in d dimensions:
 n grid points per dimension, thus n^d **grid points**
→ **curse of dimensionality**
- How to build hierarchical basis in d dimensions?
- How to build **adaptive** hierarchical approximations?
Preferably in d dimensions?
- Can we beat the curse of dimensionality using a hierarchical basis approach? \rightsquigarrow **“sparse grids”**

Part II

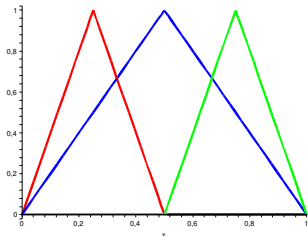
Exercises

Interpolation with Hierarchical Basis

Solve interpolation problem:

- given f_n and regular grids points x_n
- using **hierarchical basis** $\psi_k(x)$

- requiring: $f_n = \sum_{k=1}^N c_k \psi_k(x_n)$

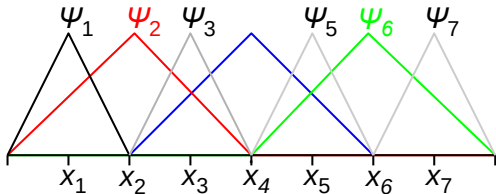


Questions:

1. set up linear system of equations to obtain c_k for $n = 3$
2. derive formulas for the c_k (depending on the f_n)
3. repeat questions 1 and 2 for $n = 7$
4. how does this extend to $n = 2^L - 1$?

Interpolation with Partly-Hierarchical Basis

Consider new (partly hierarchical) basis:



Again, solve interpolation problem:

1. set up linear system of equations to obtain c_k for $n = 7$
2. how does this extend to $n = 2^L - 1$?
3. how does this extend to solving the interpolation problem for a hierarchical basis?