

## Python Tutorial 6: Scientific Computing with Python

### 1) Polynomial interpolation

After some hours in the lab, you manage to obtain the following measurements:

$x$	1	2	3	4	5	6	7
$y$	1	2	1.5	2	3	2.5	4

Your goal is to try to fit these data to a polynomial function of the form

$$p(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6.$$

In other words, you want to find the coefficients  $a_0, \dots, a_6$  for which  $p(x_i) = y_i$ , where  $(x_i, y_i)$  are your measurements. The theory of quantum chromodynamics predicts that the values of the coefficients are

$$\begin{aligned} a_0 &= -3., & a_1 &= 4.033, & a_2 &= 1.968, \\ a_3 &= -2.885, & a_4 &= 1.024, & a_5 &= -0.147, & a_6 &= 0.00763 \end{aligned}$$

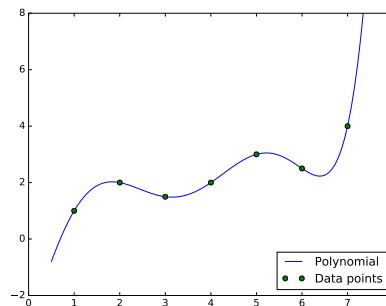


Figure 1: Polynomial interpolation of data points.

1. Create two NumPy Arrays  $x$  and  $y$  to store the measured data.
2. Plot the values using green circles.
3. The coefficients  $a_i$  can be found by solving the following system of linear equations  $Ax = b$ :

$$\begin{pmatrix} 1 & x_0 & x_0^2 & \dots & x_0^n \\ 1 & x_1 & x_1^2 & \dots & x_1^n \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^n \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{pmatrix}$$

Create a matrix  $A$  and a vector  $b$  with the values from the equation.

4. Solve the system of equations using the function `scipy.linalg.solve(A,b)`.
5. Try to reproduce Figure 1.
6. An alternative method to compute the interpolation coefficients is by using the function `scipy.polyfit()`. Look up the reference for this function and use it to compute the coefficients  $a_i$ .  
Hint: Pay attention to the order (or usage) of the coefficients in `scipy.polyfit()`.

## 2) Fitting arbitrary functions

On the course website you can find a file called `data.txt`. This file contains two columns of data: the first column is the time  $t_i$  and the second is a set of measurements  $y_i$ . We now want to find the coefficients  $p^* = (p_0, p_1, p_2, p_3) \in \mathbb{R}^4$  corresponding to the function

$$f(t) = p_0 \cos\left(\frac{2\pi}{p_1}t - p_2\right) + p_3t,$$

that minimize the least squares error with respect to our data:

$$p^* = \arg \min_{p \in \mathbb{R}^4} \sum_{i=0}^n (f(t_i) - y_i)^2.$$

In other words, we want to find the parameters  $p$  of  $f$  that fit our data best, in the sense that they minimize the above expression (see Fig. 2). This is a common task in numerical mathematics, so there are many functions that do exactly this. Use the function `scipy.optimize.leastsq` to find the optimal parameters  $p$  to fit the data (look up the documentation). Plot your results using `matplotlib`.

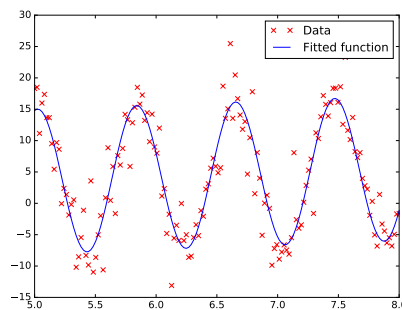


Figure 2: Fitting a sine function in the least squares sense.