

# Scientific Computing

## Continuous Models: Ordinary Differential Equations

### First-Order vs. Higher-Order ODEs

An ordinary differential equation of the form

$$f(t, y(t), dy/dt, d^2y/dt^2, \dots, d^n y/dt^n) = 0 \quad (1)$$

is called ODE of order  $n$ , i.e. the index of the highest derivative corresponds to the order of the ODE. In order to facilitate the analysis of ODEs, every ODE of order  $n > 1$  can be transformed into a system of ODEs of order  $n = 1$  as follows:

1. Assume our ODE from Eq. (1) to have order  $n > 1$ . Then, we can introduce helper functions  $y_0, \dots, y_{n-1}$ :

$$\begin{aligned} y_0(t) &:= y(t) \\ y_1(t) &:= \frac{dy(t)}{dt} \\ &\vdots \\ y_{n-1} &= \frac{d^{n-1}y(t)}{dt^{n-1}} \end{aligned}$$

2. Using the helper functions, we can transform the ODE from Eq. (1) into the following system of ODEs:

$$\begin{aligned} \frac{dy_0}{dt} &= y_1 \\ \frac{dy_1}{dt} &= y_2 \\ &\vdots \\ f\left(t, y_0, \frac{dy_0}{dt}, \frac{dy_1}{dt}, \dots, \frac{dy_{n-1}}{dt}\right) &= 0 \end{aligned}$$

The latter system only consists of first-order derivatives with respect to the helper functions.

### Exercise 11: Transformation of Higher-Order ODEs

Consider the ODE

$$\frac{d^2y}{dt^2} = -y \quad (2)$$

which should be defined on an interval  $t \in [0, \pi/2]$ .

- (a) Determine the order of this ODE.
- (b) Transform the ODE into a system of first-order ODEs. Write the transformed system as

$$\begin{pmatrix} \frac{dy_0}{dt} \\ \vdots \\ \frac{dy_{n-1}}{dt} \end{pmatrix} = A \cdot \begin{pmatrix} y_0 \\ \vdots \\ y_{n-1} \end{pmatrix} \quad (3)$$

with matrix  $A \in \mathbb{R}^{n \times n}$ .

- (c) Similar to the one-dimensional case, *homogeneous systems of ODEs*, that is ODEs which are of the form from Eq. (3), can be solved analytically using the exponential function for matrices. In case of Eq. (3) and initial conditions  $y_0(0) = c_0, y_1(0) = c_1, \dots, y_{n-1}(0) = c_{n-1}$ , the solution is given by:

$$\begin{pmatrix} y_0(t) \\ \vdots \\ y_{n-1}(t) \end{pmatrix} = \exp(A \cdot t) \begin{pmatrix} c_0 \\ \vdots \\ c_{n-1} \end{pmatrix} \quad (4)$$

Use the results from exercise 10 to determine the general solution of Eq. (2). Which information is required to obtain a unique solution? Sketch at least two approaches to obtain a unique solution for the given ODE!

### Exercise 12: Critical Points and Direction Fields for Two-Dimensional ODE Systems

- (a) Consider the ODE from Eq. (2) and its respective matrix-vector form (Eq. (3)). What can you say about its critical points and stability? Draw the direction field on  $[-1; 1] \times [-1; 1]$ .
- (b) Write a maple sheet which plots the direction field to validate your theoretical results from (a).
- (c) Consider the modified ODE

$$\frac{d^2y(t)}{dt^2} = -\mu \cdot y(t)$$

with  $\mu \geq 0$ . How does the parameter  $\mu$  affect the critical point, stability and the direction field from (a)? Modify your maple sheet for this purpose.

- (d) Consider the ODE

$$\frac{d^2y(t)}{dt^2} = -\mu \cdot y(t) + \frac{dy(t)}{dt}$$

with  $\mu \in \mathbb{R} \setminus \{0\}$ . What happens to the critical point, stability and direction field in this case?