

## Population with several species - Systems of ODE

```
> restart;  
> with(DEtools): with(plots):
```

### A linear model for 2 species

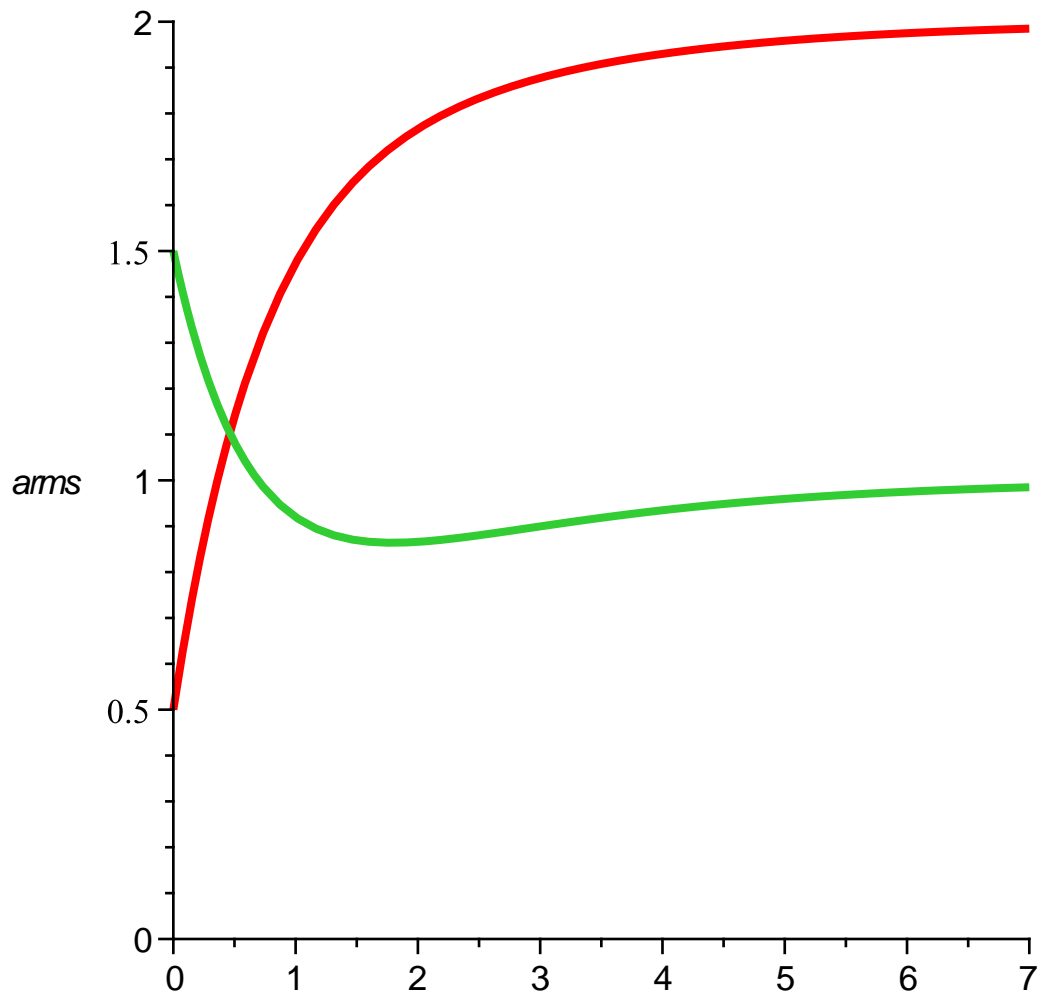
```
> twolin := { diff(p(t),t) = b1 + c1*p(t) + d1*q(t),  
              diff(q(t),t) = b2 + c2*p(t) + d2*q(t) };  
twolin := {  $\frac{d}{dt} p(t) = b1 + c1 p(t) + d1 q(t), \frac{d}{dt} q(t) = b2 + c2 p(t) + d2 q(t) \}$  (1.1)
```

### Example: arms race - steady state scenario

```
> linex1 := subs( {b1=3/2, c1=-1, d1=1/2,  
                  b2=0, c2=1/2, d2=-1},  
                  twolin);  
linex1 := {  $\frac{d}{dt} p(t) = \frac{3}{2} - p(t) + \frac{1}{2} q(t), \frac{d}{dt} q(t) = \frac{1}{2} p(t) - q(t) \}$  (1.1.1)
```

```
> linsol1 := dsolve( { op(linex1), p(0)=1/2, q(0)=3/2 }, {p  
(t), q(t)});  
linsol1 := {  $p(t) = -\frac{1}{2} e^{-\frac{1}{2}t} - e^{-\frac{3}{2}t} + 2, q(t) = -\frac{1}{2} e^{-\frac{1}{2}t} + e^{-\frac{3}{2}t} + 1 \}$  (1.1.2)
```

```
> centry1 := unapply( subs(linsol1, p(t)), t):  
centry2 := unapply( subs(linsol1, q(t)), t):  
plot([centry1,centry2],0..7,arms=0..2,thickness=3);
```



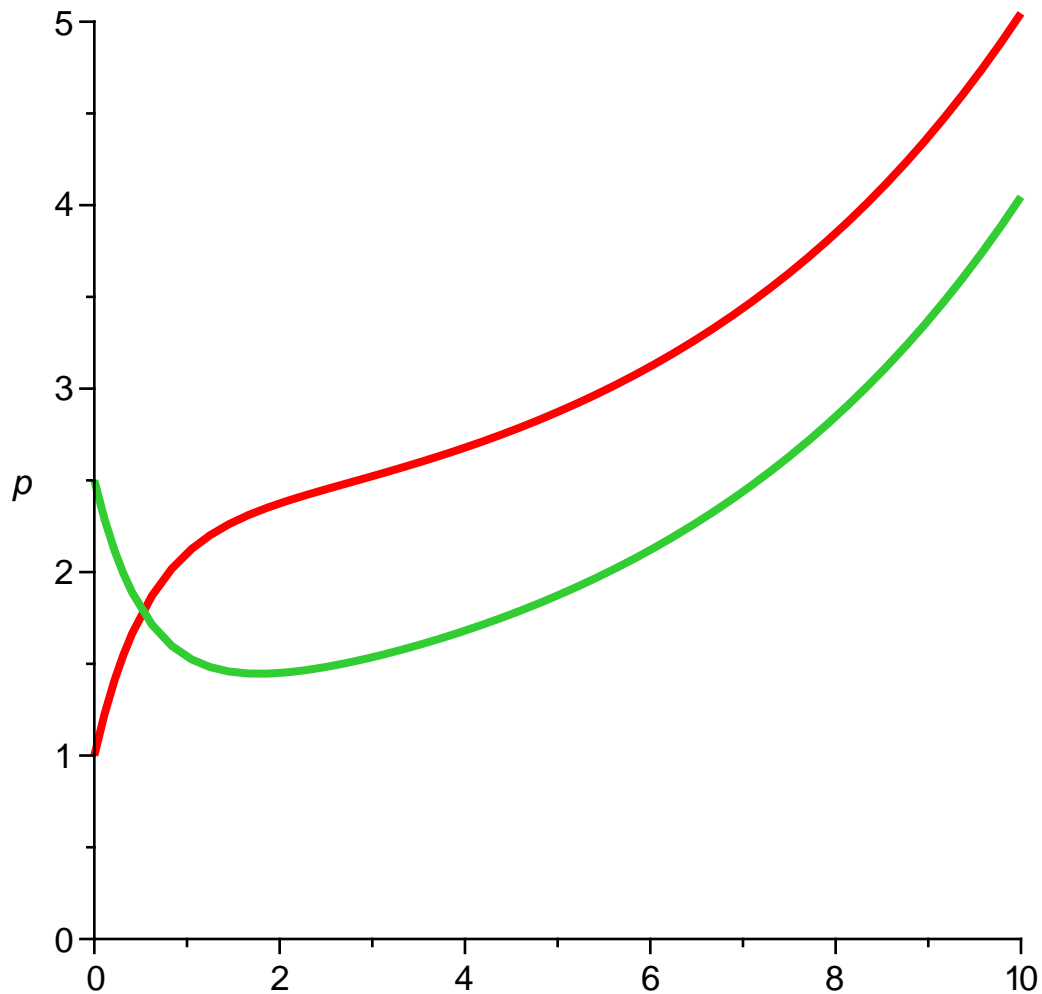
### Example: arms race - unlimited growth

```
> linex2 := subs( {b1=1/2, c1=-3/4, d1=1,
                  b2=-5/4, c2=1,    d2=-3/4},
                  twolin);
```

$$\text{linex2} := \left\{ \frac{d}{dt} p(t) = \frac{1}{2} - \frac{3}{4} p(t) + q(t), \frac{d}{dt} q(t) = -\frac{5}{4} + p(t) - \frac{3}{4} q(t) \right\} \quad (1.2.1)$$

```
> linsol2 := dsolve( { op(linex2), p(0)=1, q(0)=5/2 }, {p(t),
q(t)}):
```

```
> centry1 := unapply( subs(linsol2, p(t)), t):
   centry2 := unapply( subs(linsol2, q(t)), t):
   plot([centry1,centry2],0..10,p=0..5,thickness=3);
```



### Example: the peaceful neighbour

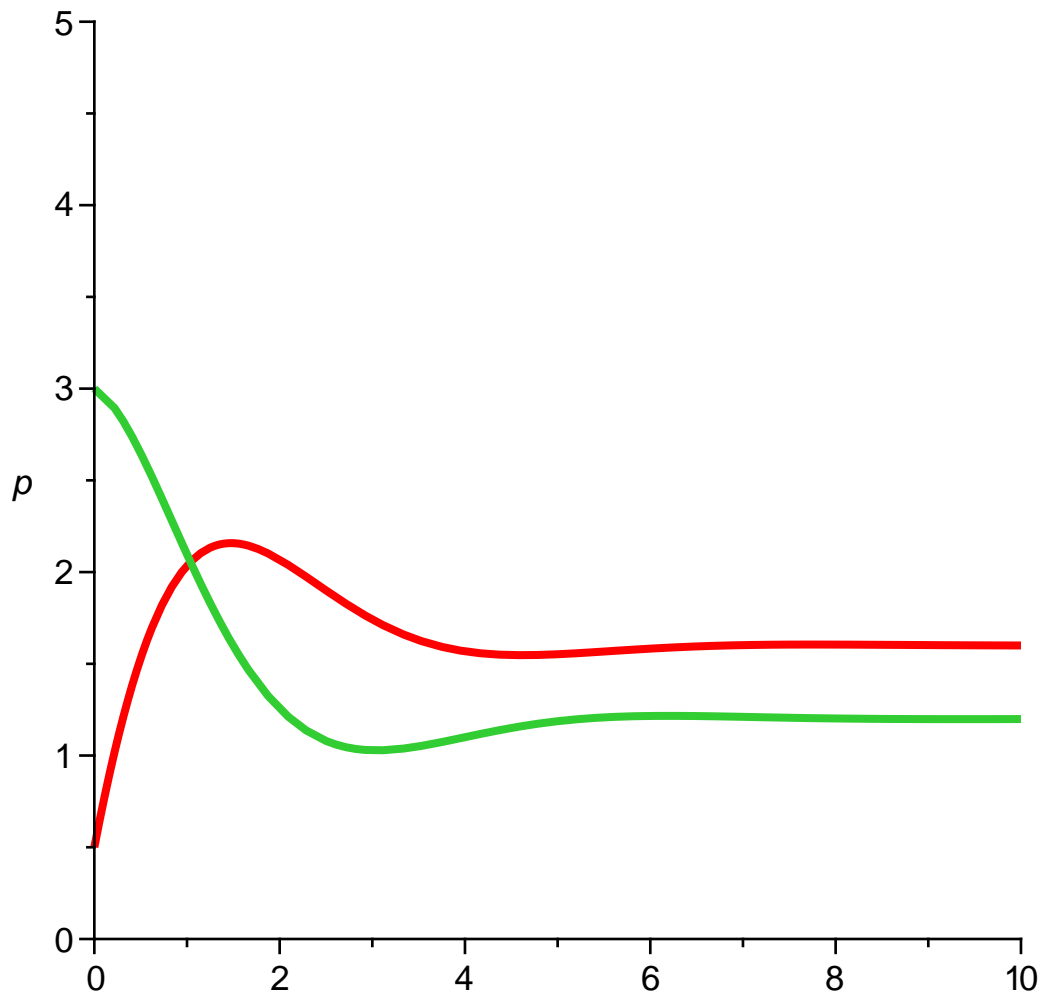
Parameter  $c_2$  is **negative**, so country 2 will destroy weapons, if its neighbour's armament grows.

```
> linex3 := subs( {b1=0, c1=-3/4, d1=1,
                  b2=5/2, c2=-1, d2=-3/4},
                 twolin);
```

$$\text{linex3} := \left\{ \frac{d}{dt} p(t) = -\frac{3}{4} p(t) + q(t), \frac{d}{dt} q(t) = \frac{5}{2} - p(t) - \frac{3}{4} q(t) \right\} \quad (1.3.1)$$

```
> linsol3 := dsolve( { op(linex3), p(0)=1/2, q(0)=3 }, {p(t),
q(t)}):
```

```
> cntry1 := unapply( subs(linsol3, p(t)), t):
cntry2 := unapply( subs(linsol3, q(t)), t):
plot([cntry1,cntry2],0..10,p=0..5,thickness=3);
```



## ▼ A non-linear model for 2 species

Here, we start from the logistic equation, and add a term for the other species:

```
> twolv := { diff(p(t),t) = ( a1 + b1*p(t) + c1*q(t) ) * p(t),
             diff(q(t),t) = ( a2 + b2*p(t) + c2*q(t) ) * q(t) }
```

$$twolv := \left\{ \begin{aligned} \frac{d}{dt} p(t) &= (a1 + b1 p(t) + c1 q(t)) p(t), \\ \frac{d}{dt} q(t) &= (a2 + b2 p(t) + c2 q(t)) q(t) \end{aligned} \right. \quad (2.1)$$

## ▼ Example: Competition - Steady State

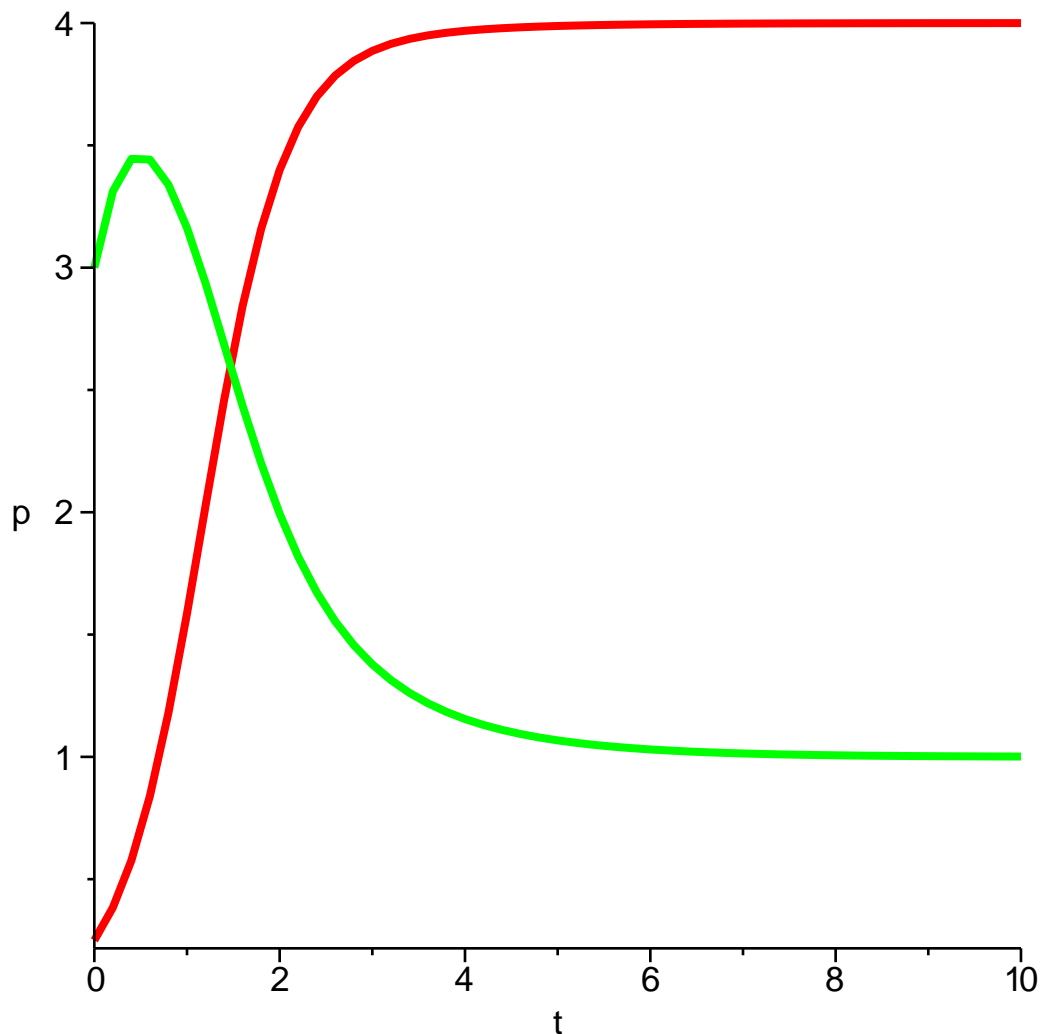
Competition between two species (sharing common resources, for example)

```
> complex1 := subs( { a1=5/2+sqrt(3)/24, b1=-5/8, c1=-sqrt(3)/24,
                    a2=7/8+sqrt(27)/2, b2=-sqrt(27)/8, c2=-7/8 },
                    twolv);
```

(2.1.1)

$$\text{compex1} := \left\{ \begin{aligned} \frac{d}{dt} p(t) &= \left( \frac{5}{2} + \frac{1}{24} \sqrt{3} - \frac{5}{8} p(t) - \frac{1}{24} \sqrt{3} q(t) \right) p(t), \frac{d}{dt} q(t) \\ &= \left( \frac{7}{8} + \frac{3}{2} \sqrt{3} - \frac{3}{8} \sqrt{3} p(t) - \frac{7}{8} q(t) \right) q(t) \end{aligned} \right. \quad (2.1.1)$$

```
> spred := DEplot( compex1, [p,q], t=0..10, [[p(0)=1/4, q(0)=
3]],
                    stepsize=0.2, scene=[t,p], linecolor=red):
spgre := DEplot( compex1, [p,q], t=0..10, [[p(0)=1/4, q(0)=
3]],
                    stepsize=0.2, scene=[t,q], linecolor=
green):
display([spred,spgre]);
```



### Example: Competition - Extinction

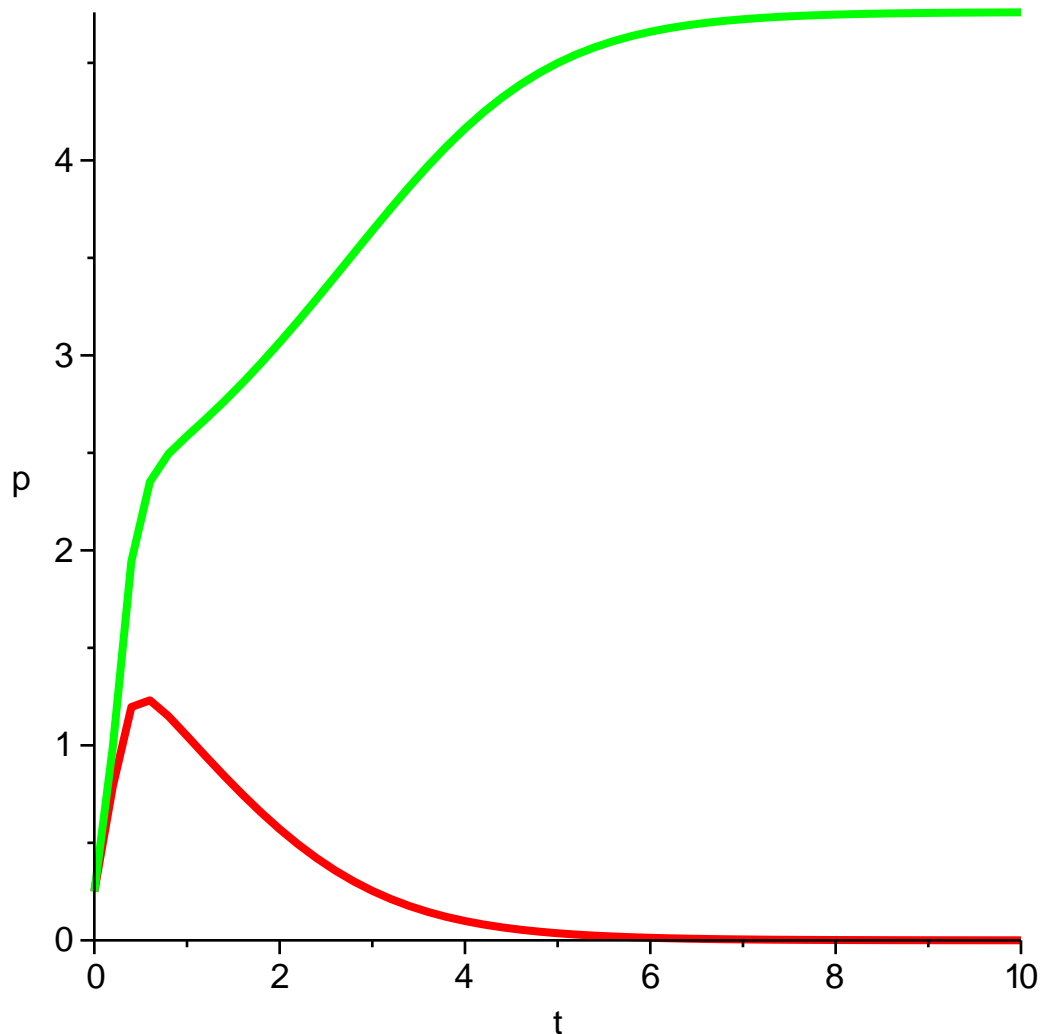
In this example, one species dies out:

```
> compex2 := subs( {a1=71/8, b1=-23/12, c1=-25/12,
                    a2=73/8, b2=-25/12, c2=-23/12},
                    twolv);
```

(2.2.1)

$$\text{compex2} := \left\{ \begin{aligned} \frac{d}{dt} p(t) &= \left( \frac{71}{8} - \frac{23}{12} p(t) - \frac{25}{12} q(t) \right) p(t), & \frac{d}{dt} q(t) &= \left( \frac{73}{8} \right. \\ & \left. - \frac{25}{12} p(t) - \frac{23}{12} q(t) \right) q(t) \end{aligned} \right\} \quad (2.2.1)$$

```
> spred := DEplot( compex2, [p,q], t=0..10, [[p(0)=1/4, q(0)=
1/2]],
                    stepsize=0.2, scene=[t,p], linecolor=red):
spgre := DEplot( compex2, [p,q], t=0..10, [[p(0)=1/4, q(0)=
1/4]],
                    stepsize=0.2, scene=[t,q], linecolor=
green):
display([spred,spgre]);
```



### ▼ A non-linear model for 2 species (predator-prey): Volterra-Lotka

```
> twospec := { diff(p(t),t) = ( b1 + c1*q(t)) * p(t),
                diff(q(t),t) = ( b2 + c2*p(t)) * q(t) };
```

(3.1)

$$twospec := \left\{ \frac{d}{dt} p(t) = (b1 + c1 q(t)) p(t), \frac{d}{dt} q(t) = (b2 + c2 p(t)) q(t) \right\} \quad (3.1)$$

```
> tsex1 := subs( {b1=-1/2, b2=1/5,
                 c1=1/200, c2=-1/50},
                 twospec);
```

$$tsex1 := \left\{ \frac{d}{dt} p(t) = \left( -\frac{1}{2} + \frac{1}{200} q(t) \right) p(t), \frac{d}{dt} q(t) = \left( \frac{1}{5} - \frac{1}{50} p(t) \right) q(t) \right\} \quad (3.2)$$

The non-linear equation is too difficult to be solved by Maple.

We use Maple's numerical method, instead:

```
> pred := DEplot( tsex1, [p,q], t=0..100, [[p(0)=6, q(0)=50]],
                 stepsize=0.2, scene=[t,p], linecolor=red):
```

```
> prey := DEplot( tsex1, [p,q], t=0..100, [[p(0)=6, q(0)=50]],
                 stepsize=0.2, scene=[t,q], linecolor=blue):
```

```
> display([pred,prey]);
```

